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### Reduction of Spatially Correlated Speckle in Textured SAR Images

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ABSTRACT Synthetic aperture radars (SARs) provide a lot of images that can be used for numerous applications. A problem with acquired images is that they are corrupted by speckle which is a noise-like phenomenon with multiplicative nature. In addition, speckle is non-Gaussian and it is often spatially correlated. A typical task in SAR image processing is despeckling and many methods have been already proposed. However, most of them do not take noise spatial correlation into account during denoising. In this paper, we show how this can be done in despeckling based on discrete cosine transform. The use of frequency-dependent thresholds leads to sufficient improvement of denoising efficiency in terms of visual quality metrics. Moreover, we consider quite complex structure texture images for which noise removal is usually problematic and can lead to information loss. Comparison to the well-known local statistic Lee and Frost filters, extended DCT-based filter is carried out for different remote sensing systems including Sentinel-1 and Sentinel-2.

**KEYWORDS** Synthetic aperture radar image; Denoising; Despeckling efficiency; Visual quality.

#### I. INTRODUCTION

ADAR remote sensing that is currently mostly Represented by airborne and spaceborne synthetic aperture radars is widely employed in various applications [1-3]. Modern SARs are able to acquire images during day and night as well as in bad weather conditions with appropriate spatial resolution of several meters. The problem of SAR images is that they suffer from noise-like phenomenon called speckle [4-6]. This problem has been understood for many years started from fundamental works of J.-S. Lee [7] and V. Frost [8]. The necessity of efficient despeckling of SAR images has been mentioned in numerous papers [9-11]. Filters that belong to different groups have been proposed starting from scanning window ones [7, 8, 12], continued by denoisers based on orthogonal transforms [13, 14], and finalized by modern non-local approaches [15-17]. Their performance steadily improves but it is still desired to suppress speckle and preserve heterogeneities (details, edges, textures) better. The practical cases for which a limited success has been gained are complex structure

images (those ones containing a lot of edges and fine details and/or highly textured ones) corrupted by spatially correlated speckle. The main reasons for this are the following. Firstly, it is hard to reach high efficiency of filtering for complex structure images (see examples in Fig. 1) even potentially [18-20]. Meanwhile, texture features and fine details have to be preserved at image denoising stage [21, 22]. Secondly, it is especially difficult to discriminate texture and noise if noise is spatially correlated since both statistical and spatial characteristics of signal and noise are quite similar. Thirdly, the case of spatially correlated noise is paid much less attention than a simpler case of white noise. In this sense, it is worth mentioning the papers [14, 23-25] specially devoted to considering reduction of spatially correlated noise.

Thus, our primary goal is to analyze despeckling efficiency for highly textured images corrupted by spatially correlated speckle. Note that speckle is spatially correlated for images acquired by such modern SAR systems as TerraSAR-X (see examples in Fig. 1) and Sentinel-1 [13] (see examples in Fig. 2). The novelty of the presented results

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is that we show how spatial correlation of the speckle can be taken into account in despeckling based on discrete cosine transform (DCT) and evaluate the benefits quantitatively with particular attention to highly textured images.

The paper structure is the following. In Section 2, we briefly analyze an image/noise model and its main properties. Section 3 deals with criteria of image despeckling efficiency. Simulation data and their analysis are given in Section 4. Real data example is given as well. Finally, the conclusions are presented.

#### **II. IMAGE/NOISE MODEL**

A traditional model of SAR images is based on assumption that speckle is pure multiplicative [4, 7-10] that has been confirmed by many tests [4, 6]. Then, the noisy (acquired) image is then described as  $I_{ij}^{sp} = I_{ij}^{true} \mu_{ij}$ , i.e. the product of a true value and random multiplicative factor where ij are indices of image pixels. For pure multiplicative noise, it is assumed that speckle has constant (relative) variance equal to  $\sigma_{\mu}^2 = 0.273/L$  where *L* is the number of looks. For real life data, this parameter can be either determined using a priori information on operation principles and characteristics of a given SAR, or experimentally as  $\delta_{\mu_{ij}}^2 = \sigma_{ij}^2 / \bar{I}_{ij}^2 \sigma_{\mu}^2$ , where  $\sigma_{ii}^2$  is the local variance estimate determined for a manually or automatically chosen homogeneous image region and  $\overline{I}_{ij}^2$  is the mean for this fragment.  $\sigma_{\mu}^2$  varies within the limits from 0 to 1 depending SAR characteristics, for single look amplitude speckle  $\sigma_u^2 = 0.273$  – this is just the case in Fig. 1 where many parts (regions) of the image in Fig. 1(b) can be used for getting the speckle variance estimate.

Fig. 2 gives examples of SAR image fragments acquired by Sentinel-1 for two polarizations: vertical-vertical (vv) and vertical-horizontal (vh). Red color squares show manually chosen fragments for which speckle variance has been estimated and occurred to be slightly larger than 0.05 (i.e. L is about 5). Spatial correlation of the speckle can be characterized in different manner. It is possible to estimate two-dimensional (2D) autocorrelation function for manually chosen quasi-homogeneous regions of a certain size (e.g., 32×32 or 64×64 pixels). However, in our case, it is better to estimate 8×8 spectrum in discrete cosine transform (DCT) domain. The reasons for this are the following. Firstly, this spectrum is needed in DCT-based denoising adapted to noise properties (see the details in Section 4). Secondly, for such size, spectrum estimates can be averaged well since it is usually quite easy to find quasi-homogeneous image regions totally containing thousands of pixels.





Figure 1. Single-look SAR image fragments of complex (a) and simple (b) structures



(a)





Figure 2. SAR image fragments of vv (a) and vh (b) polarizations with marked homogeneous regions

Examples of normalized DCT spectrum estimates for image fragments in Fig. 2 are given in Fig. 3. Here some explanations are needed. Small indices correspond to low spatial frequencies. Thus, spectrum is, obviously, non-uniform that evidences in favor of conclusion that speckle in spatially correlated.



Figure 3. DCT spectrum estimates for vv (a) and vh (b) polarization images

Then, to get quantitative evaluation of speckle suppression efficiency, we need means for modelling speckle with the determined properties. Methods to do this have been earlier described in our papers [23, 26]. In Fig. 4, we give an example of noise-free and three noisy images with spatially correlated speckle with different properties.





Figure 4. Noise-free test image (a) and its noisy versions for single-look speckle (b) and five looks with smaller (c) and higher (d) degrees of spatial correlation

Noise-free image, see Fig. 4(a) contains homogeneous regions and many objects of different shapes and contrasts with respect to surrounding background as well as fine details. Image in Fig. 4(b) corresponds to the case of amplitude single-look speckle with low degree of spatial correlation. Obviously, many small-sized objects (especially if they have low contrast) cannot be easily recognized. Fig. 4(c) shows the image with the same spatial correlation properties of speckle but with L=5. The image looks more pleasant compared to the image in Fig. 4(b) and more small-sized objects can be reliably detected and localized. Fig. 4(d) presents 5-look image but with speckle with considerably larger degree of spatial correlation than in image in Fig. 4(c). Its appearance (visual quality) is sufficiently worse and it is difficult to judge what image is better, in Fig. 4(b) or 4(d).

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This example shows one more problem with spatially correlated noise in general and speckle in particular. Images corrupted by noise with higher degree of spatial correlation are perceived as those one having worse visual quality. Thus, in addition to traditional criteria of original image quality and efficiency of their denoising, it is worth applying visual quality criteria. Note that it is still a question what are the best visual quality criteria for applicable in SAR image analysis and processing. Obviously, this should be metrics applicable for grayscale images and possessing good adequateness with respect to peculiarities of human vision system (HVS). In this sense, we can further employ earlier experience [22, 26] concerning visual quality metrics [27-30] and their use in SAR image processing [26].

Alongside with test images given in Fig. 4, we are more interested in special kinds of textural images. This is because it is known that the task of improving image quality due to denoising is the hardest just for highly textured images [18, 26]. One way to simulate them is to apply fractals. Another way is to use images acquired by Sentinel-2. Two examples of noise-free images are represented in Fig. 5. Their noisy versions with noise having properties similar to Sentinel-1 images are shown in Fig. 6. Fig. 7 gives an example of the image with many details. Obviously, noise distorts textures and, simultaneously, texture masks noise. The task is then to remove noise with texture feature preservation.



(b) Figure 5. Examples of noise-free textures



Figure 6. Noisy versions of images in Fig. 5 with PSNR about 17.5 dB (a), PSNR-HVS-M is about 14.8 dB (b)



Figure 7. Noise-free (a) and noisy (b) images with many details, PSNR=19.5 dB, PSNR-HVS-M=16.9 dB

#### III. QUANTITATIVE CRITERIA AND PRINCIPLE OF DCT-BASED DENOISING

One traditional criterion – peak signal-to-noise ratio (PSNR) – has been already mentioned. In simulations, it can be determined as

$$PSNR^{inp} = 10\log_{10}(D^2 / MSE^{inp}), \qquad (1)$$

$$MSE^{inp} = \sum_{i=1}^{I} \sum_{j=1}^{J} (I_{ij}^{noise} - I_{ij}^{true})^2 / (IJ), \qquad (2)$$

where I and J determine image size, D is image representation dynamic range equal to 255 in the considered case. PSNR is expressed in dB where a larger value relates to a better quality.

Another used metric is PSNR-HVS-M (http://www.ponomarenko.info/psnrhvsm.htm) based on HVS. The following two important properties of HVS are exploited: a higher sensitivity to distortions in low spatial frequencies and masking effect. These effects are incorporated in calculation of MSE-HVS-M used in calculation of PSNR-HVS-M as

$$PSNR - HVS - M^{inp} =$$

$$10\log_{10}(D^2 / MSE_{HVS-M}^{inp}),$$
(3)

Suppose now that we have despeckled images  $\{I_{ij}^{d}, i = 1, ..., I, j = 1, ..., J\}$ . Then it is possible to calculate

$$MSE^{d} = \sum_{i=1}^{I} \sum_{j=1}^{J} (I_{ij}^{d} - I_{ij}^{true})^{2} / (IJ),$$
(4)

$$PSNR^{d} = 10\log_{10}(D^{2}/MSE^{d}), \qquad (5)$$

$$PSNR - HVS - M^d =$$

$$10\log_{10}(D^2/MSE_{HVS-M}^{d}), \tag{6}$$

where MSE<sub>HVSM</sub> is calculated for filtered and noise-free images. PSNR-HVS-M is also expressed in dB and its larger values correspond to better visual quality.

Having input and output values of the considered metrics, it is possible to calculate their improvements as:

$$\delta PSNR = PSNR^{d} - PSNR^{inp}, \tag{7}$$

$$\delta PSNR - HVS - M = PSNR - HVS - M^{d} - PSNR - HVS - M^{inp}, \qquad (8)$$

where both improvements are in dB and their larger values, in general, correspond to more efficient denoising.

We have numerous options in choosing filters for efficiency analysis [22]. Even though many filters are not suited for multiplicative noise removal, preliminary homomorphic transform of logarithmic type can be used to convert pure multiplicative noise into pure additive [20] (although not Gaussian). Meanwhile, many filters can not be directly adapted to suppression of spatially correlated noise and this might make worse their performance. Due to this obstacle, we further consider DCT-based filters [13] that can be easily adapted to both multiplicative nature and spatial correlation of speckle.

More in detail, image despeckling is carried out in the following four steps. Firstly, direct 2D DCT is performed for each 8×8 pixel block. In this way, 64 DCT coefficients are obtained. Secondly, they are thresholded (only the DCTcoefficient relating to the block mean is kept unchanged). Several variants of thresholding are possible. Here we consider hard thresholding. For conventional DCT-filter, for block the threshold each nm-th is set as  $T(n,m) = \beta \sqrt{f(\bar{I}(n,m))}$  where  $\beta$  denotes the filter parameter commonly set equal to 2.7,  $\bar{I}(n,m)$  denotes the local mean in the block,  $f(\bar{I}(n,m))$  is the function that characterizes dependence of the local variance on local mean; then, for pure multiplicative noise one has  $T(n,m) = \beta \sqrt{f(\bar{I}(n,m))}$ . For the modified DCT-based filter [13, 26] adapted to speckle spatial correlation, one has frequency dependent thresholds defined as  $T(n,m,k,l) = \beta \sigma_{\mu} \overline{I}(n,m) \sqrt{W(k,l)}$ where W(k,l), k = 0,...,7; 0,...,7 is the aforementioned normalized power DCT spectrum for 8×8 pixels. Then, inverse 2D DCT in each block is applied to thresholded DCT at the third step. This leads to obtaining preliminary filtered values for all pixels belonging to a given block. Note that filtering is usually performed for fully overlapping blocks. This means that neighbor block positions differ by only one pixel in horizontal or vertical directions. Then, a given pixel in most cases belongs to 64 blocks and many preliminary denoised values correspond to it. Usually, these values are averaged for each given pixel and a final filtered value is obtained (this is treated as the fourth step). Let us call this version of DCT-based filter as spatial spectrum adapted (SSA) one. In general, the DCT-based denoising with full overlapping is the most efficient option (among possible variants) - it provides minimal output MSE and MSE<sub>HVS-M</sub>. Below we consider DCT-based filters with full overlapping of blocks. Note that due to existence of fast algorithms, the filters are very fast.

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#### **IV. ANALYSIS OF EXPERIMENTAL RESULTS**

Therefore, we consider the performance of conventional and SSA versions of the DCT-based filter. For comparison purpose, we have also analyzed data for the following well-known denoising techniques: the local statistic  $5 \times 5$  and 7x7 Lee filter [7] as well as 5x5 and 7x7 Frost filter [8].

Fig. 8 shows the 5x5 Lee filter outputs for images given in Fig. 6. Noise is suppressed and there are considerable improvements of PSNR and PSNR-HVS-M. Meanwhile, there is some smearing observed in output images.







Output images for two versions of DCT filters are presented in Figs 9 and 10. Analysis of images in Fig. 9 shows that noise suppression is poor and improvements are less than for the Lee filter. Artifacts are observed. Thus, conventional DCT-based filter is not worth applying. Analysis of output images in Fig. 10 shows that noise suppression is much better and this version outperforms the local statistic Lee filter both in terms of PSNR and PSNR-HVS-M. However, there are specific artifacts in the form of small vertical or horizontal "sticks" that are not "detected" by the quality criteria used but which are undesired. This shows that, in additional to quantitative criteria (metrics) analysis, visual inspection is worth applying.



Figure 9. Conventional DCT-based filter outputs for noise images in Fig. 6: PSNR=23.3 dB, PSNR-HVS-M=18.7 dB (a); PSNR=23.3 dB, PSNR-HVS-M=18.8 dB (b)





Figure 10. SSA DCT-based filter outputs for noise images in Fig. 6: PSNR=26.7 dB, PSNR-HVS-M=22.5 dB (a); PSNR=25.9 dB, PSNR-HVS-M=21.8 dB (b)



Table 1 gives simulation results for despeckling the test image in Fig. 6(a) for all considered filters. Output values of PSNR, PSNR-HVS-M and FSIM [27] are given (the larger the better). In turn, Table 2 presents data for the test image in Fig. 6(b).

As one can see, all the considered filters improve the image quality according to the used quality metrics and this improvement is sufficient. Meanwhile, the results for the modified DCT filter are the best or very close to the best.

Table 1. Comparison data for despeckling the image in Fig. 6(a); input FSIM is equal to 0.611

Filter type	Output	Output PSNR-	Output FSIM
	PSNR	HVS-M	
5x5 Lee	24.1	19.3	0.776
7x7 Lee	25.5	21.0	0.828
5x5 Frost	23.8	18.9	0.769
7x7 Frost	25.1	20.4	0.820
DCT	23.3	18.6	0.755
SSA DCT	26.7	22.5	0.827

Table 2. Comparison data for despeckling the image in Fig. 6(b); input FSIM is equal to 0.692

Filter type	Output	Output PSNR-	Output FSIM
	PSNR	HVS-M	
5x5 Lee	24.2	19.7	0.819
7x7 Lee	25.0	20.7	0.839
5x5 Frost	23.9	19.3	0.814
7x7 Frost	24.7	20.2	0.836
DCT	23.4	18.9	0.800
SSA DCT	25.9	21.8	0.835

Consider now the filter outputs for the test image with more details (Fig. 7). The image denoised by the 5x5 Lee filter is depicted in Fig. 11. PSNR improvement is almost 4 dB, improvement of PSNR-HVS-M is about 3 dB. The outputs for the two versions of DCT-based filter are given in Fig. 12. Again, the conventional version (Fig. 12(a) does not perform well since criteria improvements are quite small. The SSA DCT-based filter output is presented in Fig. 12(b). Improvements of metrics' values are considerable (they are sufficiently greater than improvements for the 5x5 Lee filter). Noise suppression is clearly visible (compare to images in Fig. 7). However, artifacts are again visible as well.



Figure 11. Lee filter outputs for noise image in Fig. 7(b): PSNR=23.4 dB, PSNR-HVS-M=19.9 dB



(b)

Figure 12. DCT-based filters' outputs for noise images in Fig. 7: PSNR=23.8 dB, PSNR-HVS-M=19.9 dB (a); PSNR=25.0 dB, PSNR-HVS-M=21.4 dB (b)

Let us give the obtained quantitative data (Table 3). Here we can observe the case when 5x5 Lee, 5x5 Frost, and standard DCT filters produce practically the same quality outputs. Meanwhile, the modified version adapted to speckle spatial correlation clearly outperforms all aforementioned filters.

Table 3.	Comparison	data for d	lespeckling	the image in
	Fig. 7(b); inp	ut FSIM i	is equal to 0.	.761

Filter type	Output PSNR	Output PSNR- HVS-M	Output FSIM
5x5 Lee	23.5	20.0	0.831
7x7 Lee	23.2	19.5	0.806
5x5 Frost	23.5	19.9	0.831
7x7 Frost	23.4	19.7	0.818
DCT	23,7	19.9	0.831
SSA DCT	25.9	21.5	0.840

Finally, Fig. 13 presents a fragments of real life example. VV-polarization Sentinel-1 image with five looks is given in Fig. 13(a). The SSA DCT-filter output is shown in Fig. 13(b). As one can see, speckle is suppressed well whilst textures, edges, and small-sized objects are preserved.

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Figure 13. Original (noisy) SAR image (a) and the SSA DCT filter output (b)

The presented examples show the following:

1) The DCT-based filter is able to preserve textures quite well (in particular, sufficiently better than the local statistic Lee filter) but only if it is adapted to spatial spectrum of spatially correlated noise;

2) In analysis of filter performance, visual inspection is needed since visual quality metrics can evidence in favor of some filters without taking into account the fact that some undesired artifacts are observed in output images; the DCTbased filter adapted to speckle properties produces artifacts that are undesired and can be treated (detected) as low contrast small-sized objects at further stages of SAR image processing.

3) We expect that modifications of nonlocal filters adapted to speckle properties [15, 23] can improve despeckling performance according to the metrics used (both traditional and visual quality ones) and the artifacts will be either absent or less seen; probably, not only processing in blocks, but also block search algorithm should be adapted to spatial correlation of the speckle.

#### **V. CONCLUSIONS**

The task of removal of spatially correlated speckle in textured images is considered. It is demonstrated that, in general, such noise can be suppressed with improvement of PSNR by up to 5-8 dB. Visual quality improves as well. Meanwhile, the sufficient positive effect can be reached if speckle spectral properties are taken into account. This can be done in DCT-based filtering by setting frequency dependent (and, simultaneously, intensity dependent) thresholds. At the same time, if one neglects speckle spatial

correlation, this can result in considerable difference between attained and potential efficiencies of denoising. Besides, one has to be careful with artifacts since they can be present even if quantitative criteria show high efficiency of filtering.

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